City University of Hong Kong Course Syllabus

offered by Department of Biomedical Engineering / Department of Mechanical Engineering with effect from Semester A 2018 / 19

Part I Course Overview

| Course Title: | Computer Controlled Systems |
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| Course Code: | MBE6002 |
| Course Duration: | 1 semester |
| Credit Units: | 3 credits |
| Level: | P6 |
| Medium of Instruction: | English |
| Medium of Assessment: | English |
| Prerequisites : (Course Code and Title) | Nil |
| Precursors : (Course Code and Title) | Background knowledge in Control Principles or equivalent |
| Equivalent Courses : (Course Code and Title) | MEEM6002 Computer Controlled Systems |
| Exclusive Courses : (Course Code and Title) | Nil |

Part II Course Details

1. Abstract

This course aims to develop an in-depth understanding of real-time control of automated sys-tems using digital computers. The objective is for students to learn how to apply control theory in implementation with computers. The mathematical techniques will be introduced for discrete domain analysis and design. It will enhance students' skills for analysis, design and imple-mentation of control systems.

2. Course Intended Learning Outcomes (CILOs)

(CILOs state what the student is expected to be able to do at the end of the course according to a given standard of performance.)

| No. | CILOs | Weighting (if applicable) | Discovery-enriched curriculum related learning outcomes (please tick where appropriate) | | | |
|----------|---|---------------------------------|---|----------|----|--|
| | | | A1 | A2 | A3 | |
| 1. | to give an account of the fundamentals of digital control and control implementation using digital computer. | | √ | ~ | | |
| 2. | to analyze discrete-time systems using z-transform. | | ~ | ~ | | |
| 3. | to design discrete-time control systems using z-plane and frequency domain methods. | | | ~ | ~ | |
| 4. | to apply state-space based controller design for discrete time systems. | | | ~ | ~ | |
| 5. | to adapt digital control design methods to controller design for systems such as robots, industrial equipment and processes. | | | ~ | ~ | |
| <u> </u> | | N.A. | | | | |

A1: Attitude

Develop an attitude of discovery/innovation/creativity, as demonstrated by students possessing a strong sense of curiosity, asking questions actively, challenging assumptions or engaging in inquiry together with teachers.

A2: Ability

Develop the ability/skill needed to discover/innovate/create, as demonstrated by students possessing critical thinking skills to assess ideas, acquiring research skills, synthesizing knowledge across disciplines or applying academic knowledge to self-life problems.

A3: Accomplishments

Demonstrate accomplishment of discovery/innovation/creativity through producing /constructing creative works/new artefacts, effective solutions to real-life problems or new processes.

3. Teaching and Learning Activities (TLAs)

(TLAs designed to facilitate students' achievement of the CILOs.)

| TLA | LA Brief Description | | LO N | 0. | | | Hours/week (if applicable) |
|----------|--|---|------|----|---|---|----------------------------|
| | | 1 | 2 | 3 | 4 | 5 | |
| Lecture | The main teaching activities will be in the form of lectures but the lectures are sometimes broken up with small group discussions where students work with their neighbors before feeding back the results to the class. | ✓ | ~ | ~ | × | | 2 hrs/week |
| Tutorial | Tutorials are problem-solving sessions and are sometimes broken up into small group discussions. | • | • | • | • | | 1 hr/week |

4. Assessment Tasks/Activities (ATs)

(ATs are designed to assess how well the students achieve the CILOs.)

| Assessment Tasks/Activities | CILO No. | | | | | Weighting | Remarks |
|--|--------------|---|---|--------------|---|-----------|---------|
| | 1 | 2 | 3 | 4 | 5 | | |
| Continuous Assessment: 40% | | | | | | | |
| Mini-project | \checkmark | ✓ | ✓ | \checkmark | ✓ | 20% | |
| Assignment/ Test | ✓ | ✓ | ✓ | ✓ | ✓ | 20% | |
| Examination: 60% (duration: 2.5 hours) | | | | | | | |
| | | | | | | 100% | |

For a student to pass the course, at least 30% of the maximum mark for both coursework and examination should be obtained.

5. Assessment Rubrics

(Grading of student achievements is based on student performance in assessment tasks/activities with the following rubrics.)

| Assessment Task | Criterion | Excellent | Good | Fair | Marginal | Failure |
|----------------------------------|---|-------------|-------------|-------------|----------|--|
| | | (A+, A, A-) | (B+, B, B-) | (C+, C, C-) | (D) | (F) |
| 1. Examination | Written exam at the end of the semester. | High | Significant | Moderate | Basic | Not even reaching marginal levels |
| 2. Mid-term and In-class Quiz | To test students' understanding of the topics during the course of the lecture. | High | Significant | Moderate | Basic | Not even reaching marginal levels |
| 3. Homework | Pass or fail to see students attitudes and ability. | High | Significant | Moderate | Basic | Not even reaching marginal levels |

Part III Other Information (more details can be provided separately in the teaching plan)

1. Keyword Syllabus

(An indication of the key topics of the course.)

Digital control fundamentals, z-transform, z-plane analysis of discrete-time systems, design of discrete-time control systems, control implementation using computers, controller design using state feedback, robot control.

2. Reading List

2.1 Compulsory Readings

(Compulsory readings can include books, book chapters, or journal/magazine articles. There are also collections of e-books, e-journals available from the CityU Library.)

N.A.

2.2 Additional Readings

(Additional references for students to learn to expand their knowledge about the subject.)

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| 1. | K. Ogata, Discrete-Time Control Systems, Prentice Hall, Inc. |
| 2. | K. J. Astrom and B. Wittenmark, Computer Controlled Systems, Prentice Hall, Inc. |
| 3. | R. G. Jacquot, Modern Digital Control Systems, Marcel Dekker. |
| 4. | F. Franklin, J. J. Powell and M. L. Workman, Digital Control of Dynamic Systems, Addison |
| | Wesley |
| 5. | Jaulin, Luc, Automation for robotics, Hoboken, N.J.: Wiley, 2015 |
| 6. | Niku Saeed B, Introduction to Robotics : Analysis, Control, Applications, Hoboken : |
| | John Wiley Inc, 2015. |
| 7. | F. L. Lewis, C. T. Abdallah and D. M. Dawson, Control of robot manipulators, Macmillan |
| | Publishing Co. |
| 8. | Dinwiddie, Keith, Basic Robotics, Boston, MA : Cengage Learning, TJ211 .D569 |
| | 2015 |